# Symmetry of immersed surfaces in euclidean 3-space

# Thomas Tucker, Colgate University, joint with Undine Leopold, Northeastern University

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Here we restrict our attention to general position immersions  $f: S \to E^3$ , where every point of S has a disk neighborhood D such that f|D is a homeomorphism onto its image and these disks meet the way two or three coordinate planes do in  $\mathbb{R}^3$ .

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We will talk briefly about more general immersions later.

# History

The question has been considered for embedded surfaces by Rüedy (1971, rotation), TT (Field's Notes to appear, all orientation-preserving), Ko(1993 for bordered surfaces), Costa (1997 anticonformal and 2011 dihedral), Lin (1979, dihedral).

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Only TT does platonic groups. No one does immersed (so all orientable, except bordered).

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Remember that a 3-page book containts a möbius strip so a figure-eight torus does too.

# The Riemann-Hurwitz equation

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$$\mathsf{RH:} \ \chi(S) = |G|(\chi(T) - \Sigma(1 - 1/r_i))$$

where branch point *i* in T has order  $r_i$ .

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The equation RH does not classify actions of G on the surface S, but it is a first step.

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For *n*-fold rotational symmetry we get:

 $\mathsf{RRH} : \chi(S) = n\chi(T) - b(n-1)$ 

where *b* is even.

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For even 
$$\chi(T) = -n - 2$$
, we have  
 $\pi(T) = \langle x_1, y_1, \dots x_n, y_n, w, z : \Pi[x_i, y_i] z w z^{-1} w = 1 \rangle$   
where  $\pi^o(T) = \langle x_1, y_1, \dots x_n, y_n, w, z^2 \rangle$ .

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Notice that any structure you have on T lifts to S (e.g polyhedral, Riemann surface, smooth), even the nature of the singularities. This is so much better than building models.

Theorem for rotation with branching

There are three cases: S, T both orientable (OO), both nonorientable (NN), S orientable but T not (ON).

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**Theorem** If  $b \neq 0$ , then RRH always realizable for OO and NN; never realizable for ON. Moreover, for OO can be an embedding.

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ON impossible since  $q_*(\pi^o(T-B))$  generates  $\pi(E^3 - Y)$ .

**Theorem** Suppose b = 0 (necessarily  $\chi(T) \le 0$ ). (OO): RRH always realizable and *S* embedded.

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In each case, b, c, d have the same parity (to be explained). Since  $A_4$  and  $A_5$  have no index two subgroup, ON is possible only for PRH and CRH.

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Notice that now, either the origin is inside q(T) (as homology 2-cycle) or outside.

In the orbifold  $E^3/G$  the set of X of rotation axes gets taken to a set Y of 3 rays from the origin.

For all but the tetrahedron and odd order prisms, there is antipodal symmetry so each axis gets bent in half.

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Thus number of branch points of each type have same parity (odd if origin inside, even if origin outside).

Theorem for at least two kinds of branching

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**Proof** Start with sphere intersecting axes correct number of times. Then add orientable handles for OO or crosscaps for NN. For ON, we have  $\pi(E^3 - Y)$  is free of rank two and generated by little loops on q(T) around axes, which are necessarily orientable, so  $q_*(\pi^o(T))$  generates  $\pi(E^3/G - Y)$  so  $\phi(\pi^o(T))$  not index two.

When there is no branching, clearly we need  $\chi(T) \leq 0$ . But if  $\chi(T) = 0$ , then since  $\pi(E^3/G - Y)$  is free and  $\pi(T)$  is 2-generator not free,  $q_*(T)$  is infinite cyclic, so  $\phi$  cannot be onto (as G is 2-generator).

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Some work in NN to show exceptions impossible. Need  $\pi(E^3 - Y)$  is free and look carefully at presentations of  $\pi(T)$ . For ON, the real point is that for odd  $\chi(T)$ , there will always be a orientation-reversing element z with  $q_*(z) = 1$ .

# Only one kind of branching

Everything OK for  $\chi(T) \leq 0$ , but for  $\chi(T) = 1, 2$  trouble if number of branch points at least 4 (necessarily even since). See example.

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Look at actions with reflections. Now orbifold has boundary.

But look out. Maybe "immersion" of S into  $E^3$  is just a covering of S onto an embedded surface S' in  $E^3$ . Now you are asking whether, say, cyclic action on S' lifts to S.